On the rate of convergence of a deep recurrent neural network estimate in a regression problem with dependent data *

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Abstract

A regression problem with dependent data is considered. Regularity assumptions on the dependency of the data are introduced, and it is shown that under suitable structural assumptions on the regression function a deep recurrent neural network estimate is able to circumvent the curse of dimensionality.

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1. Introduction

1.1. Scope of this paper

Motivated by the huge success of deep neural networks in applications (see, e.g., Schmidhuber (2015), Rawat and Wang (2017), Hewamalage, Bergmeir and Bandara (2020) and the literature cited therein) there is nowadays a strong interest in showing theoretical properties of such estimates. In the last years many new results concerning deep feed-forward neural network estimates have been derived (cf., e.g., Eldan and Shamir (2016), Lu et al. (2020), Yarotsky (2018) and Yarotsky and Zhevnerchuk (2019) concerning approximation properties or Kohler and Krzyżak (2017), Bauer and Kohler (2019) and Schmidt-Hieber (2020) concerning statistical properties of these estimates). But basically no theoretical convergence results are known about the recurrent neural network estimates, which are among those neural network estimates which have been successfully applied in practice for time series forecasting (Smyl (2020), Mas and Carre (2020) and Makridakis, Spiliotis and Assimakopolulos (2018)), handwriting recognition (Graves et

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al. (2008), Graves and Schmidhuber (2009)), speech recognition (Graves and Schmidhuber (2005), Graves, Mohamed and Hinton (2013)) and natural language processing (Pennington, Socher and Manning (2014)). For survey of the recent advances on recurrent neural networks see Salehinejad et al. (2018). In this paper we introduce a special class of deep recurrent neural network estimates and analyze their statistical properties in the context of regression estimation problem with dependent data.

1.2. A regression problem with dependent data

In order to motivate our regression estimation problem with dependent data, we start by considering a general time series prediction problem with exogeneous variables described as follows: Let (X_t, Y_t) $(t \in \mathbb{Z})$ be $\mathbb{R}^d \times \mathbb{R}$ -valued random variables which satisfy

$$Y_t = F(X_t, (X_{t-1}, Y_{t-1}), (X_{t-2}, Y_{t-2}), \dots) + \epsilon_t$$
(1)

for some measurable function $F : \mathbb{R}^d \times (\mathbb{R}^d \times \mathbb{R})^{\mathbb{N}} \to \mathbb{R}$ and some real-valued random variables ϵ_t with the property

$$\mathbf{E}\{\epsilon_t | X_t, (X_{t-1}, Y_{t-1}), (X_{t-2}, Y_{t-2}), \dots\} = 0 \quad a.s.,$$
(2)

where \mathbb{R} and \mathbb{N} are real numbers and positive integers, respectively. Given the data

$$\mathcal{D}_n = \{ (X_1, Y_1), \dots, (X_n, Y_n) \}$$
(3)

the aim is to construct an estimate $m_n(\cdot) = m_n(\cdot, \mathcal{D}_n) : \mathbb{R}^d \to \mathbb{R}$ such that the mean squared prediction error

$$\mathbf{E}\left\{|Y_{n+1}-m_n(X_{n+1},\mathcal{D}_n)|^2\right\}$$

is as small as possible.

In this article we simplify the above general model by imposing five main constraints. Firstly, we assume that $F(X_t, (X_{t-1}, Y_{t-1}), (X_{t-2}, Y_{t-2}), ...)$ does not depend on the complete infinite past $(X_{t-1}, Y_{t-1}), (X_{t-2}, Y_{t-2}), ...$ but only on the last k times steps, where $k \in \mathbb{N}$. Secondly, we assume that $F(X_t, (X_{t-1}, Y_{t-1}), (X_{t-2}, Y_{t-2}), ...)$ depends only on the x-values. Thirdly, we assume that F has, in addition, a special recursive structure:

$$F(X_t, (X_{t-1}, Y_{t-1}), (X_{t-2}, Y_{t-2}), \dots) = G(X_t, H_k(X_{t-1}, X_{t-2}, \dots, X_{t-k}))$$

where

$$H_k(x_{t-1}, x_{t-2}, \dots, x_{t-k}) = H(x_{t-1}, H_{k-1}(x_{t-2}, x_{t-3}, \dots, x_{t-k}))$$
(4)

and

$$H_1(x_{t-1}) = H(x_{t-1}, 0).$$
(5)

Here $G : \mathbb{R}^d \times \mathbb{R} \to \mathbb{R}$ and $H : \mathbb{R}^d \times \mathbb{R} \to \mathbb{R}$ are smooth functions. Fourthly, we assume that ϵ_t are independent and identically distributed random variables with mean zero satisfying the following sub-Gaussian assumption:

$$\mathbf{E}\left\{e^{c_1\cdot\epsilon_t^2}\right\} < \infty. \tag{6}$$

And finally we simplify our model further by assuming that X_1, X_2, \ldots are independent and identically distributed.

In this way we get the following regression problem: Let $(X_t)_{t\in\mathbb{Z}}$ be independent identically distributed random variables with values in \mathbb{R}^d and let $(\epsilon_t)_{t\in\mathbb{Z}}$ be independent identically distributed random variables with values in \mathbb{R} , which are independent of $(X_t)_{t\in\mathbb{Z}}$. Assume $\mathbf{E}\{\epsilon_t\} = 0$ and (6). Set

$$Y_t = G(X_t, H_k(X_{t-1}, \dots, X_{t-k})) + \epsilon_t$$

for some (measurable) $G : \mathbb{R}^d \times \mathbb{R} \to \mathbb{R}$ and H_k defined by (4) and (5) for some (measurable) $H : \mathbb{R}^d \times \mathbb{R} \to \mathbb{R}$. Given the data (3) we want to construct an estimate

$$m_n(\cdot) = m_n(\cdot, \mathcal{D}_n) : \mathbb{R}^d \times (\mathbb{R}^d)^k \to \mathbb{R}$$

such that

$$\mathbf{E}\left\{\left|Y_{n+1} - m_n(X_{n+1}, X_n, \dots, X_{n-(k-1)})\right|^2\right\}$$

is as small as possible.

In the above model we have

$$\mathbf{E}\{Y_t|X_t = x_t, \dots, X_{t-k} = x_{t-k}\} = G(x_t, H_k(x_{t-1}, \dots, x_{t-k})),$$

i.e.,

$$m(x_1, \dots, x_{k+1}) = G(x_{k+1}, H_k(x_k, \dots, x_1))$$
(7)

is the regression function on

$$((X_1,\ldots,X_{k+1}),Y_{k+1}),$$

and our estimation problem above is a standard regression estimation problem where we try to estimate (7) from the data

$$((X_1, \ldots, X_{k+1}), Y_{k+1}), ((X_2, \ldots, X_{k+2}), Y_{k+2}), \ldots, ((X_{n-k}, \ldots, X_n), Y_n).$$
 (8)

Here the data (8) is not independent because each of the variables X_2, \ldots, X_{n-1} occur in several of the data ensembles.

1.3. A recurrent neural network estimate

We construct a recurrent neural network estimate as follows: Below we define a suitable class \mathcal{F}_n of recurrent neural networks and use the least squares principle to define our estimate by

$$\tilde{m}_n = \arg\min_{f \in \mathcal{F}_n} \frac{1}{n-k} \sum_{t=k+1}^n |Y_t - f(X_t, X_{t-1}, \dots, X_{t-k})|^2$$
(9)

and

$$m_n(X_{n+1}, \mathcal{D}_n) = T_{\beta_n} \tilde{m}_n(X_{n+1}, X_n, \dots, X_{n-(k-1)})$$
(10)

where $T_L z = \min\{\max\{z, -L\}, L\}$ (for L > 0 and $z \in \mathbb{R}$) is a truncation operator and $\beta_n = c_2 \cdot \log n$.

So it remains to define the class \mathcal{F}_n of recurrent neural networks. Here we use standard feedforward neural networks with additional feedback loops. We start by defining our artificial neural network by choosing the so-called activation function $\sigma : \mathbb{R} \to \mathbb{R}$, for which we select the ReLU activation function

$$\sigma(z) = \max\{z, 0\} \quad (z \in \mathbb{R}).$$
(11)

Our neural network consists of L layers of hidden neurons with k_l neurons in layer l. It depends on a vector of weights $w_{i,j}^{(l)}$ and $\bar{w}_{j,(r,\bar{l})}^{(l)}$, where $w_{i,j}^{(l)}$ is the weight between neuron j in layer l-1 and neuron i in layer l, and where $\bar{w}_{j,(r,\bar{l})}^{(l)}$ is the recurrent weight between neuron r in layer \bar{l} and neuron j in layer l. For each neuron j in layer l the index set $I_j^{(l)}$ describes the neurons in the neural network from which there exists a recurrent connection to this neuron. The function corresponding to this network evaluated at x_1, \ldots, x_t is defined recursively as follows:

$$f_{net,\mathbf{w}}(t) = \sum_{j=1}^{k_L} w_{1,j}^{(L)} \cdot f_j^{(L)}(t), \qquad (12)$$

where

$$f_{j}^{(l)}(t) = \sigma \left(\sum_{s=1}^{k_{l-1}} w_{j,s}^{(l)} \cdot f_{s}^{(l-1)}(t) + I_{\{t>1\}} \cdot \sum_{(r,\bar{l})\in I_{j}^{l}} \bar{w}_{j,(r,\bar{l})}^{(l)} \cdot f_{r}^{(\bar{l})}(t-1) \right)$$
(13)

for $l = 2, \ldots, L$ and

$$f_j^{(1)}(t) = \sigma \left(\sum_{s=0}^d w_{j,s}^{(1)} \cdot x_t^{(s)} + I_{\{t>1\}} \cdot \sum_{(r,\bar{l})\in I_j^1} \bar{w}_{j,(r,\bar{l})}^{(1)} \cdot f_r^{(\bar{l})}(t-1) \right).$$
(14)

Here we have set $x_t^{(0)} = 1$. In case that $f_{net,\mathbf{w}}$ is computed as above we define

$$f_{net,\mathbf{w}}(X_t, X_{t-1}, \dots, X_{t-k})$$

as $f_{net,\mathbf{w}}(k+1)$ where the function is evaluated at $X_{t-k}, X_{t-k+1}, \ldots, X_t$. Here we set in (14) $x_{k+1} = X_t, x_k = X_{t-1}, \ldots, x_1 = X_{t-k}$.

In order to describe the above neural networks completely (up to the weights, which are chosen in data-dependent way by the least squares principle as described in (9)) we have to choose the number L of hidden layers, the numbers of hidden neurons k_1, k_2, \ldots , k_L in layers 1, 2, ..., L, and the location of the recurrent connections described by the index sets $I_j^{(l)}$. We set $L = L_{n,1} + L_{n,2}$, $k_l = K_{n,1}$ for $l = 1, \ldots, L_{n,1}$ and $k_l = K_{n,2}$ for $l = L_{n,1} + 1, \ldots, L_{n,1} + L_{n,2}$, where $L_{n,1}, L_{n,2}, K_{n,1}, K_{n,2}$ are parameters of the estimate chosen in Theorem 1 below. The location of the recurrent connections is described in Figure 1, which sketches the architecture of the recurrent network (see Section 2 for a formal definition).



Figure 1: The structure of the recurrent neural networks. The solid arrows are standard feedforward connections, the dashed arrows represent the recurrent connections. The two boxes represent the parts of the network which approximate functions G and H. Here H is approximately computed in layers $1, \ldots, L_{n,1}$, and function G is approximately computed in layers $L_{n,1} + 1, \ldots, L_{n,1} + L_{n,2}$.

1.4. Main result

In Theorem 1 we show that the recurrent neural network regression estimate (9) and (10) with the above class of recurrent neural networks satisfies in case that G and H are (p_G, C_G) and (p_H, C_H) -smooth the error bound

$$\mathbf{E}\left\{\left|Y_{n+1} - m_n(X_{n+1}, X_n, \dots, X_{n-(k-1)})\right|^2\right\}$$

$$\leq \min_{g: (\mathbb{R}^d)^{k+1} \to \mathbb{R}} \mathbf{E}\left\{\left|Y_{n+1} - g(X_{n+1}, \dots, X_{n-(k-1)})\right|^2\right\} + c_3 \cdot (\log n)^6 \cdot n^{-\frac{2 \cdot \min\{p_g, p_H\}}{2 \cdot \min\{p_g, p_H\} + (d+1)}}$$

Here the derived rate of convergence depends on d + 1 and not on the dimension $(k+1) \cdot (d+1)$ of the predictors in the data set (8). This shows that by using recurrent neural networks it is possible to get under the above assumptions on the structure of H_k a rate of convergence which does not depend on k (and hence circumvents the curse of dimensionality in this setting).

1.5. Discussion of related results

The Recurrent Neural Networks (RNN) are the class of artificial neural networks which can be described by the directed cyclic or acyclic graph and which exhibit temporal dynamic behaviour. Such networks can implement time delays and feedback loops. They are able to learn long-term dependencies from sequential and time-series data. In particular, properly trained RNN can model an arbitrary dynamical system. The most popular architectures of RNN are Hopfield networks in which all connections are symmetric (Bruck (1990)), Bidirectional Associative Memory, that stores associative data as vectors (Kosko (1988)), Recursive Neural Networks in which the same set of weights are applied recursively over the structured input (Socher et al. (2011)), Long-Short Term Memory (LSTM), a network able to model long-term dependencies which has been very popular in natural language processing and speech recognition (Hochreiter and Schmidhuber (1997)) and is more robust to vanishing gradients than the classical RNN, and Gated Recurrent Units which are derived from RNN by adding gating units to them (Cho et al. (2014)) and which are more capable to learn long-term dependencies and are more robust to vanishing gradients than the classical RNN. Deep RNN have been surveyed by Schmidhuber (2015). Recent advances on RNN have been discussed in Salehinejad et al. (2018). The main problems with training RNNs by backpropagation are overfitting and vanishing gradients. Overfitting has generally been controlled by regularization, dropout, activation stabilization and hidden activation preservation, see Srivastava et al (2014) and Krueger et al. (2016). Theoretical analysis of RNNs learning has been lacking to date.

1.6 Notation

Throughout the paper, the following notation is used: The sets of natural numbers, natural numbers including 0, integers and real numbers are denoted by \mathbb{N} , \mathbb{N}_0 , \mathbb{Z} and \mathbb{R} , respectively. For $z \in \mathbb{R}$, we denote the greatest integer smaller than or equal to z by $\lfloor z \rfloor$, and $\lceil z \rceil$ is the smallest integer greater than or equal to z. Let $D \subseteq \mathbb{R}^d$ and let $f : \mathbb{R}^d \to \mathbb{R}$ be a real-valued function defined on \mathbb{R}^d . We write $x = \arg\min_{z \in D} f(z)$ if $\min_{z \in \mathcal{D}} f(z)$ exists and if x satisfies $x \in D$ and $f(x) = \min_{z \in \mathcal{D}} f(z)$. For $f : \mathbb{R}^d \to \mathbb{R}$

$$||f||_{\infty} = \sup_{x \in \mathbb{R}^d} |f(x)|$$

is its supremum norm, and the supremum norm of f on a set $A \subseteq \mathbb{R}^d$ is denoted by

$$||f||_{\infty,A} = \sup_{x \in A} |f(x)|.$$

Let p = q + s for some $q \in \mathbb{N}_0$ and $0 < s \leq 1$. A function $f : \mathbb{R}^d \to \mathbb{R}$ is called (p, C)-smooth, if for every $\alpha = (\alpha_1, \ldots, \alpha_d) \in \mathbb{N}_0^d$ with $\sum_{j=1}^d \alpha_j = q$ the partial derivative $\frac{\partial^q f}{\partial x_1^{\alpha_1} \ldots \partial x_d^{\alpha_d}}$ exists and satisfies

$$\left|\frac{\partial^q f}{\partial x_1^{\alpha_1} \dots \partial x_d^{\alpha_d}}(x) - \frac{\partial^q f}{\partial x_1^{\alpha_1} \dots \partial x_d^{\alpha_d}}(z)\right| \le C \cdot \|x - z\|^s$$

for all $x, z \in \mathbb{R}^d$.

Let \mathcal{F} be a set of functions $f : \mathbb{R}^d \to \mathbb{R}$, let $x_1, \ldots, x_n \in \mathbb{R}^d$ and set $x_1^n = (x_1, \ldots, x_n)$. A finite collection $f_1, \ldots, f_N : \mathbb{R}^d \to \mathbb{R}$ is called an $L_2 \in$ -cover of \mathcal{F} on x_1^n if for any $f \in \mathcal{F}$ there exists $i \in \{1, \ldots, N\}$ such that

$$\left(\frac{1}{n}\sum_{k=1}^{n}|f(x_k) - f_i(x_k)|^2\right)^{1/2} < \varepsilon.$$

The $L_2 \varepsilon$ -covering number of \mathcal{F} on x_1^n is the size N of the smallest $L_2 \varepsilon$ -cover of \mathcal{F} on x_1^n and is denoted by $\mathcal{N}_2(\varepsilon, \mathcal{F}, x_1^n)$.

For $z \in \mathbb{R}$ and $\beta > 0$ we define $T_{\beta}z = \max\{-\beta, \min\{\beta, z\}\}$. If $f : \mathbb{R}^d \to \mathbb{R}$ is a function and \mathcal{F} is a set of such functions, then we set $(T_{\beta}f)(x) = T_{\beta}(f(x))$.

1.7. Outline of the paper

In Section 2 the deep recurrent neural network estimates used in this paper are defined. The main result is presented in Section 3 and proven in Section 4.

2. A recurrent neural network estimate

We start with the definition of our class of the recurrent neural networks. It depends on parameters k, $L_{n,1}$, $L_{n,2}$, $K_{n,1}$ and $K_{n,2}$. As activation function we use the ReLU activation function defined in (11). Depending on a weight vector \mathbf{w} which consists of weights $w_{i,j}^{(l)}$ and $\bar{w}_{j,(r,\bar{l})}^{(l)}$ we define our recurrent neural network

$$f_{net,\mathbf{w}}: (\mathbb{R}^d)^{k+1} \to \mathbb{R}$$

by

$$f_{net,\mathbf{w}}(x_{k+1}, x_k, \dots, x_1) = \sum_{j=1}^{K_{n,2}} w_{1,j}^{(L)} \cdot f_j^{(L_{n,1}+L_{n,2})}(k+1),$$

where $f_j^{(L_{n,1}+L_{n,2})}(t)$ are recursively defined as follows:

$$f_j^{(l)}(t) = \sigma \left(\sum_{s=1}^{K_{n,2}} w_{j,s}^{(l)} \cdot f_s^{(l-1)}(t) \right)$$
(15)

for $l = L_{n,1} + 2, \dots, L_{n,1} + L_{n,2}$,

$$f_{j}^{(L_{n,1}+1)}(t) = \sigma \left(\sum_{s=1}^{K_{n,1}} w_{j,s}^{(L_{n,1}+1)} \cdot f_{s}^{(L_{n,1})}(t) + I_{\{t>1\}} \cdot \sum_{s=1}^{K_{n,1}} \bar{w}_{j,(s,L_{n,1})}^{(L_{n,1}+1)} \cdot f_{s}^{(L_{n,1})}(t-1) \right),$$
(16)

$$f_j^{(l)}(t) = \sigma \left(\sum_{s=1}^{K_{n,1}} w_{j,s}^{(l)} \cdot f_s^{(l-1)}(t) \right)$$
(17)

for $l = 2, ..., L_{n,1}$ and

$$f_{j}^{(1)}(t) = \sigma \left(\sum_{s=0}^{d} w_{j,s}^{(1)} \cdot x_{t}^{(s)} + I_{\{t>1\}} \cdot \sum_{s=1}^{K_{n,1}} \bar{w}_{j,(s,L_{n,1})}^{(1)} \cdot f_{s}^{(L_{n,1})}(t-1) \right).$$
(18)

Let $\mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})$ be the class of all such recurrent deep networks. Observe that here we implement the networks in a slightly different way than in Figure 1 since



Figure 2: The structure of the recurrent neural networks in $\mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})$. The solid arrows are standard feedforward connections, the dashed arrows represent the recurrent connections. The two boxes represent the parts of the network which implement approximations of functions G and H. Here the network which approximates H also feeds the input to G.

we do not use a direct connection from the input to the part of the network in G, instead we use the network which implements H also to feed the input to G (cf., Figure 2).

Then our estimate is defined by

$$\tilde{m}_n = \arg\min_{f \in \mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})} \frac{1}{n-k} \sum_{t=k+1}^n |Y_t - f(X_t, X_{t-1}, \dots, X_{t-k})|^2$$
(19)

and

$$m_n(X_{n+1}, \mathcal{D}_n) = T_{\beta_n} \tilde{m}_n(X_{n+1}, X_n, \dots, X_{n-(k-1)}).$$
(20)

3. Main result

Our main result is described the following theorem.

Theorem 1 Let X_t $(t \in \mathbb{Z})$ be independent and identically distributed $[0, 1]^d$ -valued random variables, and let ϵ_t $(t \in \mathbb{Z})$ be independent and identically distributed \mathbb{R} -valued random variables with $\mathbf{E}{\epsilon_t} = 0$ which satisfy (6) and which are independent from $(X_t)_{t \in \mathbb{Z}}$. Let $G, H : \mathbb{R}^d \times \mathbb{R} \to \mathbb{R}$ be (p_G, C_g) - and (p_H, C_H) -smooth functions which satisfy

$$|G(x,z_1) - G(x,z_2)| \le C \cdot |z_1 - z_2| \quad and \quad |H(x,z_1) - H(x,z_2)| \le C \cdot |z_1 - z_2| \quad (21)$$

 $(x \in \mathbb{R}^d, z_1, z_2 \in \mathbb{R})$ for some constant C > 1. Let $k \in \mathbb{N}$ and define

$$Y_t = G(X_t, H_k(X_{t-1}, \dots, X_{t-k})) + \epsilon_t$$

for H_k recursively defined by (4) and (5).

Set

$$K_{n,1} = \lceil c_4 \rceil, \quad K_{n,2} = \lceil c_5 \rceil, \quad L_{n,1} = \left\lceil c_6 \cdot n^{\frac{d+1}{2 \cdot (2p_H + d+1)}} \right\rceil$$

and

$$L_{n,2} = \left\lceil c_7 \cdot n^{\frac{d+1}{2 \cdot (2p_G + d + 1)}} \right\rceil$$

and define the estimate m_n as in Section 2. Then we have for $c_4, \ldots, c_7 > 0$ sufficiently large and for any $n \ge 2 \cdot k + 2$:

$$\mathbf{E}\left\{\left|Y_{n+1} - m_n(X_{n+1}, X_n, \dots, X_{n-(k-1)})\right|^2\right\}$$

$$\leq \min_{g:(\mathbb{R}^d)^{k+1} \to \mathbb{R}} \mathbf{E}\left\{\left|Y_{n+1} - g(X_{n+1}, \dots, X_{n-(k-1)})\right|^2\right\} + c_8 \cdot (\log n)^6 \cdot n^{-\frac{2 \cdot \min\{p_G, p_H\}}{2 \cdot \min\{p_G, p_H\} + (d+1)}}$$

Remark 1. Our estimation problem can be considered as a regression problem with independent variable

$$(X_t, X_{t-1}, \ldots, X_{t-k})$$

having dimension $d \cdot k$. The rate of convergence in Theorem 1 corresponds to the optimal minimax rate of convergence of a regression problem with dimension d + 1 (cf., Stone (1982)), hence our assumption on the structure of H_t enables us to get the rate of convergence independent of k.

4. Proofs

4.1. Auxiliary results from empirical process theory

In our proof we will apply well-known techniques from the empirical process theory as described, for instance, in van de Geer (2000). We reformulate the results there by the following two auxiliary lemmas.

Let

$$Y_i = m(x_i) + W_i \quad (i = 1, \dots, n)$$

for some $x_1, \ldots, x_n \in \mathbb{R}^d$, $m : \mathbb{R}^d \to \mathbb{R}$ and some random variables W_1, \ldots, W_n which are independent and have expectation zero. We assume that the W_i 's are sub-Gaussian in the sense that

$$\max_{i=1,\dots,n} K^2 \mathbf{E} \{ e^{W_i^2/K^2} - 1 \} \le \sigma_0^2$$
(22)

for some $K, \sigma_0 > 0$. Our goal is to estimate m from $(x_1, Y_1), \ldots, (x_n, Y_n)$. Let \mathcal{F}_n be a set of functions $f : \mathbb{R}^d \to \mathbb{R}$ and consider the least squares estimate

$$\tilde{m}_n(\cdot) = \arg\min_{f \in \mathcal{F}_n} \frac{1}{n} \sum_{i=1}^n |f(x_i) - Y_i|^2 \quad \text{and} \quad m_n = T_{\beta_n} \tilde{m}_n,$$
(23)

where $\beta_n = c_2 \cdot \log n$.

Lemma 1 Assume that the sub-Gaussian condition (22) and

$$|m(x_i)| \le \beta_n/2 \quad (i = 1, \dots, n)$$

hold, and let the estimate be defined by (23). Then there exist constants $c_9, c_{10} > 0$ which depend only on σ_0 and K such that for any $\delta_n > c_9/n$ with

$$\sqrt{n} \cdot \delta \ge c_9 \int_{\delta/(12\sigma_0)}^{\sqrt{48\delta}} \left(\log \mathcal{N}_2 \left(u, \{ T_{\beta_n} f - g : f \in \mathcal{F}_n, \frac{1}{n} \sum_{i=1}^n |T_{\beta_n} f(x_i) - g(x_i)|^2 \le 4\delta \}, x_1^n \right) \right)^{1/2} du$$
(24)

for all $\delta \geq \delta_n/6$ and all $g \in \mathcal{F}_n$ we have

$$\mathbf{P}\left\{\frac{1}{n}\sum_{i=1}^{n}|m_{n}(x_{i})-m(x_{i})|^{2} > c_{10}\left(\delta_{n}+\min_{f\in\mathcal{F}_{n}}\frac{1}{n}\sum_{i=1}^{n}|f(x_{i})-m(x_{i})|^{2}\right)\right\} \\
\leq c_{10}\cdot\exp\left(-\frac{n\cdot\min\{\delta_{n},\sigma_{0}^{2}\}}{c_{10}}\right) + \frac{c_{10}}{n}.$$

Proof. Lemma 1 follows from the proof of proof of Lemma 3 in Kohler and Krzyżak (2020). For the sake of completeness a complete proof can be found in the Appendix. \Box

In order to formulate our next auxiliary result we let $(X, Y), (X_1, Y_1), \ldots$ be independent and identically distributed $\mathbb{R}^d \times \mathbb{R}$ valued random variables with $\mathbf{E}Y^2 < \infty$, and we let $m(x) = \mathbf{E}\{Y|X = x\}$ be the corresponding regression function.

Lemma 2 Let $\beta_n \geq L \geq 1$ and assume that m is bounded in absolute value by L. Let $n, N \in \mathbb{N}$, let \mathcal{F}_n be a set of functions $f : \mathbb{R}^d \to \mathbb{R}$, let

$$\tilde{m}_n(\cdot) = \tilde{m}_n(\cdot, (X_1, Y_1), \dots, (X_{n+N}, Y_{n+N})) \in \mathcal{F}_n$$

and set $m_n = T_{\beta_n} \tilde{m}_n$. Then there exist constants $c_{11}, c_{12}, c_{13}, c_{14} > 0$ such that for any $\delta_n > 0$ which satisfies

$$\delta_n > c_{11} \cdot \frac{\beta_n^2}{n}$$

and

$$c_{12} \cdot \frac{\sqrt{n\delta}}{\beta_n^2} \ge \int_{c_{13} \cdot \delta/\beta_n^2}^{\sqrt{\delta}} \left(\log \mathcal{N}_2 \left(u, \{ (T_{\beta_n} f - m)^2 : f \in \mathcal{F}_n \}, x_1^n \right) \right)^{1/2} du \quad (25)$$

for all $\delta \geq \delta_n$ and all $x_1, \ldots, x_n \in \mathbb{R}^d$, we have for $n \in \mathbb{N} \setminus \{1\}$

$$\mathbf{P}\left\{\int |m_n(x) - m(x)|^2 \mathbf{P}_X(dx) > \delta_n + 3\frac{1}{n}\sum_{i=1}^n |m_n(X_i) - m(X_i)|^2\right\}$$
$$\leq c_{14} \cdot \exp\left(-\frac{n \cdot \delta_n}{c_{14} \cdot \beta_n^2}\right).$$

Proof. The result follows from the proof of Lemma 4 in Kohler and Krzyżak (2020). For the sake of completeness a complete proof can be found in the Appendix. \Box

4.2. Approximation results for neural networks

Lemma 3 Let $d \in \mathbb{N}$, let $f : \mathbb{R}^d \to \mathbb{R}$ be (p, C)-smooth for some p = q + s, $q \in \mathbb{N}_0$ and $s \in (0, 1]$, and C > 0. Let $A \ge 1$ and $M \in \mathbb{N}$ sufficiently large (independent of the size of A, but

$$M \ge 2 \text{ and } M^{2p} \ge c_{15} \cdot \left(\max\left\{ A, \|f\|_{C^q([-A,A]^d)} \right\} \right)^{4(q+1)},$$

where

$$\|f\|_{C^q([-A,A]^d)} = \max_{\substack{\alpha_1,\dots,\alpha_d \in \mathbb{N}_0, \\ \alpha_1 + \dots + \alpha_d \leq q}} \left\| \frac{\partial^q f}{\partial x_1^{\alpha_1} \dots \partial x_d^{\alpha_d}} \right\|_{\infty,[-A,A]^d},$$

must hold for some sufficiently large constant $c_{15} \ge 1$). a) Let $L, r \in \mathbb{N}$ be such that

1.
$$L \ge 5 + \lceil \log_4(M^{2p}) \rceil \cdot (\lceil \log_2(\max\{q, d\} + 1\}) \rceil + 1)$$

2. $r \ge 2^d \cdot 64 \cdot {d+q \choose d} \cdot d^2 \cdot (q+1) \cdot M^d$

hold. There exists a feedforward neural network $f_{net,wide}$ with ReLU activation function, L hidden layers and r neurons per hidden layer such that

$$\|f - f_{net,wide}\|_{\infty,[-A,A]^d} \le c_{16} \cdot \left(\max\left\{A, \|f\|_{C^q([-A,A]^d)}\right\}\right)^{4(q+1)} \cdot M^{-2p}.$$
 (26)

b) Let $L, r \in \mathbb{N}$ be such that

1.
$$L \ge 5M^d + \left\lceil \log_4 \left(M^{2p+4 \cdot d \cdot (q+1)} \cdot e^{4 \cdot (q+1) \cdot (M^d - 1)} \right) \right\rceil$$

 $\cdot \left\lceil \log_2(\max\{q, d\} + 1) \right\rceil + \left\lceil \log_4(M^{2p}) \right\rceil$
2. $r \ge 132 \cdot 2^d \cdot \left\lceil e^d \right\rceil \cdot {d+q \choose d} \cdot \max\{q+1, d^2\}$

hold. There exists a feedforward neural network $f_{net,deep}$ with ReLU activation function, L hidden layers and r neurons per hidden layer such that (26) holds with $f_{net,wide}$ replaced by $f_{net,deep}$.

Proof. See Theorem 2 in Kohler and Langer (2020).

Lemma 4 Let $k \in \mathbb{N}$, $x_1, \ldots, x_{k+1} \in [0, 1]^d$, $A \ge 1$, $g, \hat{g} : \mathbb{R}^d \times \mathbb{R} \to \mathbb{R}$, $h : \mathbb{R}^d \times \mathbb{R} \to [-A, A]$, $\hat{h} : \mathbb{R}^d \times \mathbb{R} \to \mathbb{R}$ and assume

$$|g(x,z) - g(x,\bar{z})| \le C_{Lip,g} \cdot |z - \bar{z}|$$
 and $|h(x,z) - h(x,\bar{z})| \le C_{Lip,h} \cdot |z - \bar{z}|$

for some $C_{Lip,q}, C_{Lip,h} > 1$. Set $z_0 = \hat{z}_0 = 0$,

$$z_t = h(x_t, z_{t-1})$$
 and $\hat{z}_t = h(x_t, \hat{z}_{t-1})$

for $t = 1, \ldots, k$. Assume

$$\frac{C_{Lip,h}^{k} - 1}{C_{Lip,h} - 1} \cdot \|h - \hat{h}\|_{\infty, [-2A, 2A]^{d+1}} \le 1.$$

Then we have

$$\begin{aligned} &|g(x_{k+1}, z_k) - \hat{g}(x_{k+1}, \hat{z}_k)| \\ &\leq \|g - \hat{g}\|_{\infty, [-2A, 2A]^{d+1}} + C_{Lip, g} \cdot \frac{C_{Lip, h}^k - 1}{C_{Lip, h} - 1} \cdot \|h - \hat{h}\|_{\infty, [-2A, 2A]^{d+1}}. \end{aligned}$$

Proof. For $t \in \{1, ..., k\}$, $z_{t-1} \in [-A, A]$ and $\hat{z}_{t-1} \in [-2A, 2A]$ we have

$$\begin{aligned} |z_t - \hat{z}_t| &= |h(x_t, z_{t-1}) - \hat{h}(x_t, \hat{z}_{t-1})| \\ &\leq |h(x_t, z_{t-1}) - h(x_t, \hat{z}_{t-1})| + |h(x_t, \hat{z}_{t-1}) - \hat{h}(x_t, \hat{z}_{t-1})| \\ &\leq C_{Lip,h} \cdot |z_{t-1} - \hat{z}_{t-1}| + \|h - \hat{h}\|_{\infty, [-2A, 2A]^{d+1}}. \end{aligned}$$

In case $z_s \in [-A, A]$ and $\hat{z}_s \in [-2A, 2A]$ for $s \in \{0, 1, \dots, t-1\}$ we can conclude

$$\begin{aligned} |z_t - \hat{z}_t| \\ &\leq \|h - \hat{h}\|_{\infty, [-2A, 2A]^{d+1}} \cdot (1 + C_{Lip,h} + C_{Lip,h}^2 + \dots + C_{Lip,h}^{k-1}) + C_{Lip,h}^k \cdot |z_0 - \hat{z}_0| \\ &= \|h - \hat{h}\|_{\infty, [-2A, 2A]^{d+1}} \cdot \frac{C_{Lip,h}^k - 1}{C_{Lip,h} - 1} + 0 \leq 1 \end{aligned}$$

(where the last equality follows from $z_0 = \hat{z}_0 = 0$), which implies

$$|\hat{z}_t| \le |z_t| + |z_t - \hat{z}_t| \le A + 1 \le 2A.$$

Via induction we can conclude that we have $z_s \in [-A, A]$ and $\hat{z}_s \in [-2A, 2A]$ for $s \in \{0, 1, \ldots, k\}$ and consequently we get

$$|z_k - \hat{z}_k| \le ||h - \hat{h}||_{\infty, [-2A, 2A]^{d+1}} \cdot \frac{C_{Lip, h}^k - 1}{C_{Lip, h} - 1}.$$

This together with

$$\begin{aligned} |g(x_k, z_k) - \hat{g}(x_k, \hat{z}_k)| &\leq |g(x_k, z_k) - g(x_k, \hat{z}_k)| + |g(x_k, \hat{z}_k) - \hat{g}(x_k, \hat{z}_k)| \\ &\leq C_{Lip,g} \cdot |z_k - \hat{z}_k| + \|\hat{g} - g\|_{[\infty, -2A, 2A]^d} \end{aligned}$$

implies the assertion.

Lemma 5 Let $k \in \mathbb{N}$ and $A \geq 1$. Assume that g and h are (p_G, C_G) - and (p_H, C_H) -smooth functions which satisfy the assumptions of Lemma 4, and define

$$h_t(x_t, x_{t-1}, \dots, x_1) = h(x_t, h_{t-1}(x_{t-1}, x_{t-2}, \dots, x_1))$$

 $t=2,\ldots,k$ and

$$h_1(x_1) = h(x_1, 0).$$

Let h_{net} be a feedforward neural network with $L_{n,1}$ hidden layers and $K_{n,1}$ hidden neurons in each layer and let g_{net} be a feedforward neural network with $L_{n,2}$ hidden layers and $K_{n,2}$ hidden neurons in each layer, which approximate h and g. Let $x_1, \ldots, x_n \in [0,1]^d$ arbitrary and assume

$$||h_{net} - h||_{\infty, [-2A, 2A]^d} \cdot \frac{C_{Lip,h}^k - 1}{C_{Lip,h} - 1} \le 1.$$

Then there exists $f_{net,rec} \in \mathcal{F}(k, K_{n,1} + 2 \cdot d, K_{n,2}, L_{n,1}, L_{n,2})$ such that

$$\begin{aligned} &|g(x_{k+1}, h_k(x_k, \dots, x_1)) - f_{net, rec}(x_{k+1}, \dots, x_1)| \\ &\leq c_{17} \cdot \max\{\|g_{net} - g\|_{\infty, [-2A, 2A]^{d+1}}, \|h_{net} - h\|_{\infty, [-2A, 2A]^{d+1}}\} \end{aligned}$$

holds for any $x_{k+1}, \ldots, x_1 \in [0, 1]^d$.

Proof. We construct our recurrent neural network as follows:

In layers $1, \ldots, L_{n,1}$ it computes in neurons $1, \ldots, K_{n,1}$ $h_{net}(x, z)$, where x is the input of the recurrent neural network and z is the output of layer $L_{n,1}$ of the network in the previous time step propagated by the recurrent connections. In the same layer it uses

$$f_{id}(x) = x = \sigma(x) - \sigma(-x)$$

in order to propagate in the neurons $K_{n,1} + 1, \ldots, K_{n,1} + 2 \cdot d$ the input value of x to the next layer.

In layers $L_{n,1} + 1, \ldots, L_{n,1} + L_{n,2}$ it computes in the neurons $1, \ldots, K_{n,2}$ the function $g_{net}(x, z)$. Here the layer $L_{n,1} + 1$ gets as input the value of x propagated to the layer $L_{n,1}$ in the neurons $K_{n,1} + 1, \ldots, K_{n,1} + 2 \cdot d$ in the previous layers, and (via a recurrent connection) the output z of the network h_{net} computed in the layers $1, \ldots, L_{n,1}$ in the previous time step.

The output of our recurrent network is the output of g_{net} computed in layer $L_{n,1}+L_{n,2}$. By construction, this recurrent neural network computes

$$f_{net,rec}(x_{k+1},\ldots,x_1) = g_{net}(x_{k+1},\hat{z}_k),$$

where \hat{z}_k is recursively defined by

$$\hat{z}_t = h_{net}(x_t, \hat{z}_{t-1})$$

for $t = 2, \ldots, k$ and

$$\hat{z}_1 = h_{net}(x_1, 0).$$

From this we get the assertion by applying Lemma 4.

4.3. A bound on the covering number

Lemma 6 Let $\mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})$ be the class of deep recurrent networks introduced in Section 2 and assume

$$\max\{L_{n,1}, L_{n,2}\} \le L_n \le n^{c_{18}} \quad and \quad \max\{K_{n,1}, K_{n,2}\} \le K_n.$$

Then we have for any $z_1^s \in ((\mathbb{R}^d)^{k+1})^s$ and any $1/n^{c_{19}} < \epsilon < c_2 \cdot (\log n)/4$

$$\log \left(\mathcal{N}_2 \left(\epsilon, \{ T_{\beta_n} f : f \in \mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2}) \}, z_1^s \right) \right) \\\leq c_{20} \cdot k \cdot L_n^2 \cdot K_n^2 \cdot (\log n)^2.$$

Proof. By unfolding the recurrent neural networks in $\mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})$ in time it is easy to see that $\mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})$ is contained in a class of standard feedforward neural networks with

$$(k+1) \cdot (L_{n,1} + L_{n,2})$$

layers having at most

$$\max\{K_{n,1}, K_{n,2}\} + 2d + 2$$

neurons per layer. In this unfolded feedforward neural network there are at most

$$c_{22} \cdot (L_{n,1} \cdot K_{n,1}^2 + L_{n,2} \cdot K_{n,2}^2)$$

different weights (since we share the same weights at all time points). By Theorem 6 in Bartlett et al. (2019) we can conclude that the VC dimension of the set of all subgraphs from $\mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})$ (cf., e.g., Definition 9.6 in Györfi et al. (2002)) and hence also the VC dimension of the set of all subgraphs from

$$\{T_{\beta_n}f : f \in \mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})\}$$

is bounded above by

$$c_{22} \cdot (L_{n,1} \cdot K_{n,1}^2 + L_{n,2} \cdot K_{n,2}^2) \cdot (k+1) \cdot (L_{n,1} + L_{n,2}) \cdot \log((k+1) \cdot (L_{n,1} + L_{n,2})) \\ \leq c_{23} \cdot k \cdot L_n^2 \cdot K_n^2 \cdot \log(n).$$

From this together with Lemma 9.2 and Theorem 9.4 in Györfi et al. (2002) we can conclude

$$\mathcal{N}_{2}\left(\epsilon, \{T_{\beta_{n}}f : f \in \mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})\}, z_{1}^{k}\right)$$
$$\leq 3 \cdot \left(\frac{4e \cdot (c_{2} \cdot \log n)^{2}}{\epsilon^{2}} \cdot \log \frac{6e \cdot (c_{2} \cdot \log n)^{2}}{\epsilon^{2}}\right)^{c_{23} \cdot k \cdot L_{n}^{2} \cdot K_{n}^{2} \cdot \log(n)},$$

which implies the assertion.

4.4. Proof of Theorem 1

In the first step of the proof we show that the assertion follows from

$$\mathbf{E} \int |m_n(u,v) - G(u,H_k(v))|^2 \mathbf{P}_{X_{n+1}}(du) \mathbf{P}_{(X_n,\dots,X_{n-k+1})}(dv)$$

$$\leq (\log n)^3 \cdot n^{-\frac{2 \cdot \min\{p_G,p_H\}}{2 \cdot \min\{p_G,p_H\} + (d+1)}}.$$
 (27)

Let

$$m(x_{k+1}, x_k, \dots, x_1) = \mathbf{E}\{Y_{k+1} | X_{k+1} = x_{k+1}, \dots, X_1 = x_1\}$$

be the regression function to $((X_{k+1}, \ldots, X_1), Y_{k+1})$. By the assumptions on (X_t, Y_t) we have

$$m(x_{k+1}, x_k, \dots, x_1) = G(x_{k+1}, H_k(x_k, \dots, x_1))$$

and

$$m(x_{n+1}, x_n, \dots, x_{n-(k-1)}) = \mathbf{E}\{Y_{n+1} | X_{n+1} = x_{n+1}, \dots, X_{n-(k-1)} = x_{n-(k-1)}\},\$$

from which we can conclude by a standard decomposition of the L_2 risk in nonparametric regression (cf., e.g., Section 1.1 in Györfi et al. (2002))

$$\begin{split} \mathbf{E} \left\{ \left| Y_{n+1} - m_n(X_{n+1}, X_n, \dots, X_{n-(k-1)}) \right|^2 \right\} \\ &= \mathbf{E} \left\{ \left| (Y_{n+1} - m(X_{n+1}, X_n, \dots, X_{n-(k-1)}) + (m(X_{n+1}, X_n, \dots, X_{n-(k-1)})) - m_n(X_{n+1}, X_n, \dots, X_{n-(k-1)})) \right|^2 \right\} \\ &= \mathbf{E} \left\{ \left| Y_{n+1} - m(X_{n+1}, X_n, \dots, X_{n-(k-1)}) - m_n(X_{n+1}, X_n, \dots, X_{n-(k-1)})) \right|^2 \right\} \\ &+ \mathbf{E} \left\{ \left| m(X_{n+1}, X_n, \dots, X_{n-(k-1)}) - m_n(X_{n+1}, X_n, \dots, X_{n-(k-1)}) \right|^2 \right\} \\ &= \min_{g: (\mathbb{R}^d)^{k+1} \to \mathbb{R}} \mathbf{E} \left\{ |Y_{n+1} - g(X_{n+1}, X_n, \dots, X_{n-(k-1)})|^2 \right\} \\ &+ \mathbf{E} \int |m_n(u, v) - G(u, H_k(v))|^2 \mathbf{P}_{X_{n+1}}(du) \mathbf{P}_{(X_n, \dots, X_{n-k+1})}(dv). \end{split}$$

In the second step of the proof we show

$$\mathbf{E} \left\{ \int |m_n(u,v) - G(u,H_k(v))|^2 \mathbf{P}_{X_{n+1}}(du) \mathbf{P}_{(X_n,\dots,X_{n-k+1})}(dv) - \frac{6 \cdot k + 6}{n-k} \sum_{i=k+1}^n |m_n(X_i,X_{i-1},\dots,X_{i-k}) - m(X_i,X_{i-1},\dots,X_{i-k})|^2 \right\}$$

$$\leq c_{24} \cdot (\log n)^6 \cdot n^{-\frac{2 \cdot \min\{p_G,p_H\}}{\min\{p_G,p_H\} + d+1}}$$
(28)

 Set

$$T_n = \int |m_n(u,v) - G(u,H_k(v))|^2 \mathbf{P}_{X_{n+1}}(du) \mathbf{P}_{(X_n,\dots,X_{n-k+1})}(dv) - \frac{6 \cdot k + 6}{n-k} \sum_{i=k+1}^n |m_n(X_i,X_{i-1},\dots,X_{i-k}) - m(X_i,X_{i-1},\dots,X_{i-k})|^2.$$

Then

$$T_{n} \leq \int |m_{n}(u,v) - G(u,H_{k}(v))|^{2} \mathbf{P}_{X_{n+1}}(du) \mathbf{P}_{(X_{n},\dots,X_{n-k+1})}(dv)$$

$$-\frac{6 \cdot k + 6}{n-k} \sum_{\substack{i=k+1+l\cdot(k+1),\\l\in\mathbb{N}_{0},k+1+l\cdot(k+1)\leq n}} |m_{n}(X_{i},X_{i-1},\dots,X_{i-k}) - m(X_{i},X_{i-1},\dots,X_{i-k})|^{2}$$

$$= \int |m_{n}(u,v) - G(u,H_{k}(v))|^{2} \mathbf{P}_{X_{n+1}}(du) \mathbf{P}_{(X_{n},\dots,X_{n-k+1})}(dv)$$

$$-\frac{n_{k} \cdot (6 \cdot k + 6)}{3 \cdot (n-k)} \cdot \frac{3}{n_{k}} \sum_{\substack{i=k+1+l\cdot(k+1),\\l\in\mathbb{N}_{0},k+1+l\cdot(k+1)\leq n}} \left|m_{n}(X_{i},X_{i-1},\dots,X_{i-k}) - m(X_{i},X_{i-1},\dots,X_{i-k})\right|^{2}$$

where

$$n_k = |\{l \in \mathbb{N}_0 : k+1+l \cdot (k+1) \le n\}| \ge \left\lfloor \frac{n}{k+1} \right\rfloor \ge \frac{n}{2k+2}$$

is the number of terms in the sum on the right-hand side above and consequently

$$T_n \leq \int |m_n(u,v) - G(u,H_k(v))|^2 \mathbf{P}_{X_{n+1}}(du) \mathbf{P}_{(X_n,\dots,X_{n-k+1})}(dv) - \frac{3}{n_k} \sum_{\substack{i=k+1+l\cdot(k+1),\\l\in\mathbb{N}_0,k+1+l\cdot(k+1)\leq n}} |m_n(X_i,X_{i-1},\dots,X_{i-k}) - m(X_i,X_{i-1},\dots,X_{i-k})|^2.$$

Let $\delta_n \ge c_{25}/n$. Then

$$\mathbf{E}\{T_n\} \le \delta_n + \int_{\delta_n}^{4\beta_n^2} \mathbf{P}\{T_n > t\} \, dt.$$

We will apply Lemma 2 in order to bound $\mathbf{P}\{T_n > t\}$ for $t > \delta_n$. Here we will replace n by n_k and \mathcal{F}_n by $\mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})$. By Lemma 6 we know for $u > c_{25} \cdot \delta_n / \beta_n^2$

$$\log \mathcal{N}_2\left(u, \left\{ (T_{\beta_n}f - m)^2 : f \in \mathcal{F}_n, \frac{1}{n} \sum_{i=1}^n |T_{\beta_n}f(x_i) - m(x_i)|^2 \le \frac{\delta}{\beta_n^2} \right\}, x_1^n \right)$$

$$\leq \log \mathcal{N}_2\left(u, \left\{ (T_{\beta_n}f - m)^2 : f \in \mathcal{F}_n \right\}, x_1^n \right)$$

$$\leq \log \mathcal{N}_2\left(\frac{u}{4\beta_n}, \left\{ T_{\beta_n}f : f \in \mathcal{F}_n \right\}, x_1^n \right)$$

$$\leq c_{26} \cdot k \cdot (\max\{L_{n,1}, L_{n,2}\})^2 \cdot (\max\{K_{n,1}, K_{n,2}\})^2 \cdot (\log n)^2.$$

$$\leq c_{27} \cdot n^{\frac{(d+1)}{2 \cdot \min\{p_G, p_H\} + d + 1}} \cdot (\log n)^2.$$

Consequently (25) is satisfied for

$$\delta_n = c_{28} \cdot \frac{n^{\frac{d+1}{2 \cdot \min\{p_G, p_H\} + d+1}} \cdot (\log n)^6}{n} = c_{28} \cdot (\log n)^6 \cdot n^{-\frac{2 \cdot \min\{p_G, p_H\}}{2 \cdot \min\{p_G, p_H\} + d+1}}.$$

Application of Lemma 2 yields

$$\mathbf{E}\{T_n\} \le \delta_n + c_{29} \cdot \frac{\beta_n^2}{n} \cdot \exp\left(-\frac{n \cdot \delta_n}{c_{14} \cdot \beta_n^2}\right),\,$$

which implies (28).

In the third step of the proof we show

$$\mathbf{E}\left\{\frac{1}{n-k}\sum_{i=k+1}^{n}|m_{n}(X_{i},X_{i-1},\ldots,X_{i-k})-m(X_{i},X_{i-1},\ldots,X_{i-k})|^{2}\right\} \leq c_{30}\cdot(\log n)^{6}\cdot n^{-\frac{2\cdot\min\{p_{G},p_{H}\}}{\min\{p_{G},p_{H}\}+d+1}}.$$
(29)

To do this, we set

$$\bar{T}_n = \frac{1}{n-k} \sum_{i=k+1}^n |m_n(X_i, X_{i-1}, \dots, X_{i-k}) - m(X_i, X_{i-1}, \dots, X_{i-k})|^2$$

and define δ_n as in the second step of the proof (for c_{28} sufficiently large). Then

$$\mathbf{E}\{\bar{T}_n\} \le \delta_n + \int_{\delta_n}^{4\beta_n^2} \mathbf{P}\{\bar{T}_n > t\} \, dt.$$

To bound $\mathbf{P}\{\overline{T}_n > t\}$ for $t \ge \delta_n$, we apply Lemma 1 conditioned on X_1, \ldots, X_n and with sample size n - k instead of n and with $\mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})$ instead of \mathcal{F}_n . As in the proof of the second step we see that (24) holds for $\delta \ge \delta_n/12$. Furthermore, we get by application of Lemma 3 b) and Lemma 5

$$\min_{f \in \mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})} \frac{1}{n-k} \sum_{i=k+1}^{n} |f(X_i, X_{i-1}, \dots, X_{i-k}) - m(X_i, X_{i-1}, \dots, X_{i-k})|^2 \\
\leq \left(\min_{f \in \mathcal{F}(k, K_{n,1}, K_{n,2}, L_{n,1}, L_{n,2})} \|f - m\|_{\infty, [0,1]^d}\right)^2 \\
\leq c_{31} \cdot \max\{L_{n,1}^{-\frac{2p_H}{d+1}}, L_{n,2}^{-\frac{2p_G}{d+1}}\} \leq c_{28}/2 \cdot (\log n)^6 \cdot n^{-\frac{2 \cdot \min\{p_G, p_H\}}{\min\{p_G, p_H\} + d+1}} = \delta_n/2.$$

Consequently, we get by Lemma 1

$$\mathbf{E}\{\bar{T}_n\} \leq \delta_n + \int_{\delta_n}^{4\beta_n^2} \mathbf{P}\{\bar{T}_n > t\} dt.$$

$$\leq \delta_n + 4\beta_n^2 \cdot \mathbf{P}\{\bar{T}_n > \delta_n/2 + \delta_n/2\}$$

$$\leq \delta_n + 4\beta_n^2 \cdot c_{32} \cdot \exp(-c_{33} \cdot (n-k) \cdot \frac{\delta_n}{2}) + 4\beta_n^2 \cdot \frac{c_{34}}{n},$$

which implies (29).

In the fourth step of the proof we conclude the proof of Theorem 1 by showing (27). Define T_n and \overline{T}_n as in the second and in the third step of the proof, resp. Then (28) and (29) imply

$$\mathbf{E} \int |m_n(u,v) - G(u,H_k(v))|^2 \mathbf{P}_{X_{n+1}}(du) \mathbf{P}_{(X_n,\dots,X_{n-k+1})}(dv) \leq \mathbf{E}\{T_{n,1}\} + (6\cdot k + 6) \cdot \mathbf{E}\{T_{n,2}\} \leq c_{35} \cdot (\log n)^6 \cdot n^{-\frac{2\cdot \min\{p_G,p_H\}}{\min\{p_G,p_H\}+d+1}}.$$

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A. Proof of Lemma 1

By the Markov inequality and assumption (22) we have

$$\begin{aligned} & \mathbf{P} \left\{ \exists i \in \{1, \dots, n\} : |Y_i| > \beta_n \right\} \\ & \leq \mathbf{P} \left\{ \exists i \in \{1, \dots, n\} : |W_i| > \beta_n/2 \right\} \\ & \leq n \cdot \max_{i=1,\dots,n} \mathbf{P} \left\{ \exp(|W_i|^2/K^2) > \exp(((\beta_n/2)^2/K^2)) \right\} \\ & \leq \frac{n}{\exp((\beta_n)^2/(4K^2))} \cdot \left(1 + \frac{\sigma_0^2}{K^2}\right). \end{aligned}$$

This together with Lemma 1 in Kohler and Krzyżak (2020) implies

where we have set

$$m_n^* = \arg\min_{f \in \mathcal{F}_n} \frac{1}{n} \sum_{i=1}^n |f(x_i) - m(x_i)|^2.$$

So it remains to show

$$\mathbf{P}\left\{\frac{24}{n}\sum_{i=1}^{n}(m_{n}(x_{i})-m_{n}^{*}(x_{i}))\cdot W_{i} \geq \frac{1}{n}\sum_{i=1}^{n}|m_{n}(x_{i})-m_{n}^{*}(x_{i})|^{2}+12\cdot\delta_{n}\right\} \leq c_{37}\cdot\exp\left(-\frac{n\cdot\min\{\delta_{n},\sigma_{0}^{2}\}}{c_{37}}\right),$$

which we do next. For $f : \mathbb{R}^d \to \mathbb{R}$ set

$$||f||_n^2 = \frac{1}{n} \sum_{i=1}^n |f(X_i)|^2.$$

We have

$$\mathbf{P}\left\{\|m_n - m_n^*\|_n^2 + 12 \cdot \delta_n \le \frac{24}{n} \sum_{i=1}^n (m_n(x_i) - m_n^*(x_i)) \cdot W_i\right\} \le P_1 + P_2$$

where

$$P_1 = \mathbf{P}\left\{\frac{1}{n}\sum_{i=1}^{n}W_i^2 > 2\sigma_0^2\right\}$$

 and

$$P_2 = \mathbf{P}\left\{\frac{1}{n}\sum_{i=1}^n W_i^2 \le 2\sigma_0^2, \|m_n - m_n^*\|_n^2 + 12 \cdot \delta_n \le \frac{24}{n}\sum_{i=1}^n (m_n(x_i) - m_n^*(x_i)) \cdot W_i\right\}.$$

By the Markov inequality and assumption (22) we have

$$P_{1} = \mathbf{P} \left\{ \sum_{i=1}^{n} W_{i}^{2}/K^{2} > 2n\sigma_{0}^{2}/K^{2} \right\}$$

$$\leq \mathbf{P} \left\{ \exp\left(\sum_{i=1}^{n} W_{i}^{2}/K^{2}\right) > \exp\left(2n\sigma_{0}^{2}/K^{2}\right) \right\}$$

$$\leq \exp\left(-2n\sigma_{0}^{2}/K^{2}\right) \cdot \mathbf{E} \left\{ \exp\left(\sum_{i=1}^{n} W_{i}^{2}/K^{2}\right) \right\}$$

$$\leq \exp\left(-2n\sigma_{0}^{2}/K^{2}\right) \cdot \left(1 + \sigma_{0}^{2}/K^{2}\right)^{n}$$

$$\leq \exp\left(-2n\sigma_{0}^{2}/K^{2}\right) \cdot \exp\left(n \cdot \sigma_{0}^{2}/K^{2}\right) = \exp\left(-n\sigma_{0}^{2}/K^{2}\right).$$

To bound P_2 , we observe first that $1/n \sum_{i=1}^n W_i^2 \le 2\sigma_0^2$ together with the Cauchy-Schwarz inequality implies

$$\frac{24}{n} \sum_{i=1}^{n} (m_n(x_i) - m_n^*(x_i)) \cdot W_i \leq 24 \cdot \sqrt{\frac{1}{n} \sum_{i=1}^{n} (m_n(x_i) - m_n^*(x_i))^2 \cdot \sqrt{2\sigma_0^2}}$$

hence inside of P_2 we have

$$\frac{1}{n}\sum_{i=1}^{n}(m_n(x_i) - m_n^*(x_i))^2 \le 1152\sigma_0^2.$$

 Set

$$S = \min\{s \in \mathbb{N}_0 : 4 \cdot 2^s \delta_n > 1152\sigma_0^2\}.$$

Application of the peeling device (cf. Section 5.3 in van de Geer (2000)) yields

$$P_{2} = \sum_{s=1}^{S} \mathbf{P} \Biggl\{ \frac{1}{n} \sum_{i=1}^{n} W_{i}^{2} \le 2\sigma_{0}^{2}, 12 \cdot 2^{s-1}\delta_{n} \cdot I_{\{s \neq 1\}} \le \|m_{n} - m_{n}^{*}\|_{n}^{2} < 12 \cdot 2^{s}\delta_{n}, \\\|m_{n} - m_{n}^{*}\|_{n}^{2} + 12\delta_{n} \le \frac{24}{n} \sum_{i=1}^{n} (m_{n}(x_{i}) - m_{n}^{*}(x_{i})) \cdot W_{i} \Biggr\} \\ \le \sum_{s=1}^{S} \mathbf{P} \Biggl\{ \frac{1}{n} \sum_{i=1}^{n} W_{i}^{2} \le 2\sigma_{0}^{2}, \|m_{n} - m_{n}^{*}\|_{n}^{2} < 12 \cdot 2^{s}\delta_{n}, \end{aligned}$$

$$\frac{1}{2} \cdot 2^{s} \delta_{n} \leq \frac{1}{n} \sum_{i=1}^{n} (m_{n}(x_{i}) - m_{n}^{*}(x_{i})) \cdot W_{i} \bigg\}$$

The probabilities in the above sum can be bounded by Corollary 8.3 in van de Geer (2000) (use there $R = \sqrt{12 \cdot 2^s \delta_n}$, $\delta = \frac{1}{2} \cdot 2^s \delta_n$ and $\sigma = \sqrt{2}\sigma_0$). This yields

$$P_2 \leq \sum_{s=1}^{\infty} c_{38} \cdot \exp\left(-\frac{n \cdot (\frac{1}{2} \cdot 2^s \delta_n)^2}{4c_{60} \cdot 12 \cdot 2^s \delta_n}\right) = \sum_{s=1}^{\infty} c_{38} \cdot \exp\left(-\frac{n \cdot 2^s \cdot \delta_n}{c_{38}}\right)$$
$$\leq \sum_{s=1}^{\infty} c_{38} \cdot \exp\left(-\frac{n \cdot (s+1) \cdot \delta_n}{c_{38}}\right) \leq c_{39} \cdot \exp\left(-\frac{n \cdot \delta_n}{c_{39}}\right).$$

B. Proof of Lemma 2

For $f : \mathbb{R}^d \to \mathbb{R}$ set

$$||f||_n^2 = \frac{1}{n} \sum_{i=1}^n |f(X_i)|^2.$$

We have

$$\begin{split} \mathbf{P} &\left\{ \int |m_n(x) - m(x)|^2 \mathbf{P}_X(dx) > \delta_n + 3\frac{1}{n} \sum_{i=1}^n |m_n(X_i) - m(X_i)|^2 \right\} \\ &= \mathbf{P} \left\{ 2 \int |m_n(x) - m(x)|^2 \mathbf{P}_X(dx) - 2||m_n - m||_n^2 \\ &> \delta_n + \int |m_n(x) - m(x)|^2 \mathbf{P}_X(dx) + ||m_n - m||_n^2 \right\} \\ &\leq \mathbf{P} \left\{ \exists f \in \mathcal{F}_n : \frac{|\int |T_{\beta_n} f(x) - m(x)|^2 \mathbf{P}_X(dx) - ||T_{\beta_n} f - m||_n^2|}{\delta_n + \int |T_{\beta_n} f(x) - m(x)|^2 \mathbf{P}_X(dx) + ||T_{\beta_n} f - m||_n^2} > \frac{1}{2} \right\}. \end{split}$$

The probability above can be bounded by Theorem 19.2 in Györfi et al. (2002) (which we apply with

$$\mathcal{F} = \left\{ (T_{\beta_n} f - m)^2 : f \in \mathcal{F}_n \right\},\,$$

 $K = 4\beta_n^2, \, \epsilon = 1/2, \, \mathrm{and} \, \, \alpha = \delta_n.)$ This yields

$$P_{1,n} \le 15 \cdot \exp\left(-\frac{n \cdot \delta_n}{c_{40} \cdot \beta_n^2}\right).$$

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